

# zero-riscy: User Manual

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## **Document Revisions**

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0.1	06.06.17	P.D. Schiavone	First Draft
0.2	15.01.18	P.D. Schiavone	Fixed CSR reset values





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### 1 Introduction

ZERO-RISCY is a 2-stage in-order 32b RISC-V processor core. ZERO-RISCY has been designed to be small and efficient. Via two parameters, the core is configurable to support four ISA configurations. Figure 1 shows a block diagram of the core.

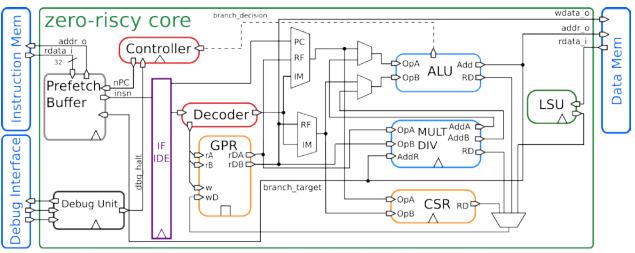


Figure 1: Block Diagram

#### 1.1 Supported Instruction Set

ZERO-RISCY supports the following instructions:

- Full support for RV32I Base Integer Instruction Set
- Full support for RV32E Base Integer Instruction Set
- Full support for RV32C Standard Extension for Compressed Instructions
- Full support for RV32M Integer Multiplication and Division Instruction Set Extension

The RV32M and RV32E can be enable and disable using two parameters.

#### 1.2 ASIC Synthesis

ASIC synthesis is supported for ZERO-RISCY. The whole design is completely synchronous and uses positive-edge triggered flip-flops, except for the register file, which can be implemented either with latches or with flip-flops. See Chapter 4 for more details about the register file. The core occupies an area of about 18.9 kGE when the latch based register file and the RV32IMC ISA is used or 11.6 kGE when the RV32EC is used .

#### 1.3 FPGA Synthesis

FPGA synthesis is supported for ZERO-RISCY when the flip-flop based register file is used. Since latches are not well supported on FPGAs, it is crucial to select the flip-flop based register file.





#### 1.4 Outline

This document summarizes all the functionality of the ZERO-RISCY core in more detail. First, the instruction and data interfaces are explained in Chapter 2 and 3. Chapter 4 explains the register file. Control and status registers are explained in Chapter 5 and Chapter 6 gives an overview of all performance counters. Chapter 7 deals with exceptions and interrupts, and finally Chapter 8 summarizes the accessible debug registers.





### 2 Instruction Fetch

The instruction fetcher of the core is able to supply one instruction to the ID stage per cycle if the instruction cache or the instruction memory is able to serve one instruction per cycle. The instruction address must be half-word-aligned due to the support of compressed instructions. It is not possible to jump to instruction addresses that have the LSB bit set.

For optimal performance and timing closure reasons, a prefetcher is used which fetches instruction from the instruction memory, or instruction cache.

Table 1 describes the signals that are used to fetch instructions. This interface is a simplified version that is used by the LSU that is described in Chapter 3. The difference is that no writes are possible and thus it needs less signals.

Signal	Direction	Description
instr_req_o	output	Request ready, must stay high until instr_gnt_i is high for one cycle
instr_addr_o[31:0]	output	Address
instr_rdata_i[31:0]	input	Data read from memory
instr_rvalid_i	input	instr_rdata_is holds valid data when instr_rvalid_i is high. This signal will be high for exactly one cycle per request.
instr_gnt_i	input	The other side accepted the request. instr_addr_o may change in the next cycle

Table 1: Instruction Fetch Signals

#### 2.1 Protocol

The protocol used to communicate with the instruction cache or the instruction memory is the same as the protocol used by the LSU. See the description of the LSU in Chapter 3.2 for details about the protocol.





## 3 Load-Store-Unit (LSU)

The LSU of the core takes care of accessing the data memory. Load and stores on words (32 bit), half words (16 bit) and bytes (8 bit) are supported.

Table 2 describes the signals that are used by the LSU.

Signal	Direction	Description
data_req_o	output	Request ready, must stay high until data_gnt_i is high for one cycle
data_addr_o[31:0]	output	Address
data_we_o	output	Write Enable, high for writes, low for reads. Sent together with data_req_o
data_be_o[3:0]	output	Byte Enable. Is set for the bytes to write/read, sent together with data_req_o
data_wdata_o[31:0]	output	Data to be written to memory, sent together with data_req_o
data_rdata_i[31:0]	input	Data read from memory
data_rvalid_i	input	data_rdata_is holds valid data when data_rvalid_i is high. This signal will be high for exactly one cycle per request.
data_gnt_i	input	The other side accepted the request. data_addr_o may change in the next cycle

Table 2: LSU Signals

#### 3.1 Misaligned Accesses

The LSU is able to perform misaligned accesses, meaning accesses that are not aligned on natural word boundaries. However, it needs to perform two separate word-aligned accesses internally. This means that at least two cycles are needed for misaligned loads and stores.

#### 3.2 Protocol

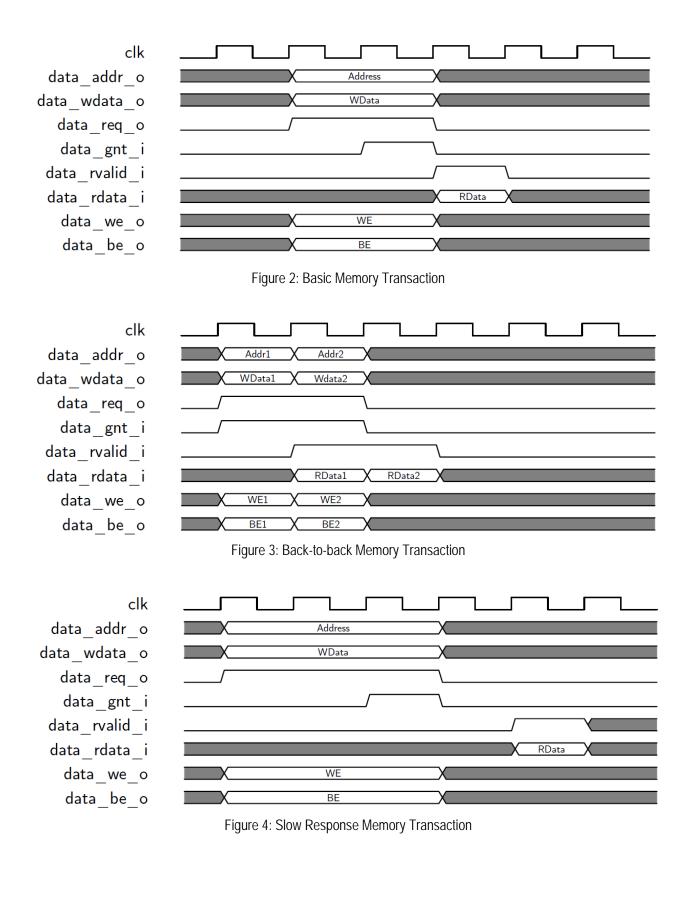
The protocol that is used by the LSU to communicate with a memory works as follows:

The LSU provides a valid address in data\_addr\_o and sets data\_req\_o high. The memory then answers with a data\_gnt\_i set high as soon as it is ready to serve the request. This may happen in the same cycle as the request was sent or any number of cycles later. After a grant was received, the address may be changed in the next cycle by the LSU. In addition, the data\_wdata\_o, data\_we\_o and data\_be\_o signals may be changed as it is assumed that the memory has already processed and stored that information. After receiving a grant, the memory answers with a data\_rvalid\_i set high if data\_rdata\_i is valid. This may happen one or more cycles after the grant has been received. Note that data\_rvalid\_i must also be set when a write was performed, although the data\_rdata\_i has no meaning in this case.

Figure 2, Figure 3 and Figure 4 show example-timing diagrams of the protocol.











### 4 Register File

ZERO-RISCY has 31 or 15 32-bit wide registers depending if the RV32E extension is enabled. Register x0 is statically bound to 0 and can only be read, it does not contain any sequential logic.

There are two flavors of register file available:

- 1. Latch-based
- 2. Flip-flop based

While the latch-based register file is recommended for ASICs, the flip-flop based register file is recommended for FPGA synthesis, although both are compatible with either synthesis target. Note the flip-flop based register file is significantly larger than the latch-based register-file for an ASIC implementation.

#### 4.1 Latch-based Register File

The latch based register file contains manually instantiated clock gating cells to keep the clock inactive when the latches are not written.

It is assumed that there is a clock gating cell for the target technology that is wrapped in a module called cluster\_clock\_gating and has the following ports:

- clk\_i: Clock Input
- en\_i: Clock Enable Input
- test\_en\_i: Test Enable Input (activates the clock even though en\_i is not set)
- clk\_o: Gated Clock Output





## 5 Control and Status Registers

ZERO-RISCY does not implement all control and status registers specified in the RISC-V privileged specifications, but is limited to the registers that were needed for the PULP system. The reason for this is that we wanted to keep the footprint of the core as low as possible and avoid any overhead that we do not explicitly need.

CSR Ad	dress	5		Hex	Name	Acc.	Description
11:10	9:8	7:6	5:0				
00	11	00	000000	0x300	MSTATUS	R/W	Machine Status
00	11	00	000101	0x305	MTVEC	R	Machine Trap-Vector Base Address
00	11	01	000001	0x341	MEPC	R/W	Machine Exception Program Counter
00	11	01	000010	0x342	MCAUSE	R/W	Machine Trap Cause
01	11	00	Oxxxxx	0x780-0x79F	PCCRs	R/W	Performance Counter Counter Registers
01	11	10	100000	0x7A0	PCER	R/W	Performance Counter Enable
01	11	10	100001	0x7A1	PCMR	R/W	Performance Counter Mode
11	11	00	010100	0xF14	MHARTID	R	Hardware Thread ID

Table 3: Control and Status Register Map

### 5.1 Machine Status (MSTATUS)

CSR Address: 0x300

Reset Value: 0x0000\_1800

31									1	2 11		-	7		3		
										$\leq$			$\leq$		~		
										PP			PIE		1E		
										-							

Detailed:

Bit #	R/W	Description
12:11	R	MPP: Statically 2'b11 and cannot be altered (read-only).
7	R/W	<b>Previous Interrupt Enable:</b> When an exception is encountered, MPIE will be set to IE. When the mret instruction is executed, the value of MPIE will be stored to IE.
3	R/W	<b>Interrupt Enable:</b> If you want to enable interrupt handling in your exception handler, set the Interrupt Enable to 1'b1 inside your handler code.





0

#### 5.2 Machine Trap-Vector Base Address (MTVEC)

CSR Address: 0x305



When an exception is encountered, the core jumps to the corresponding handler using the content of the MTVEC as base address. It is a read-only register which contains the boot address.

Table 3: MTVEC

#### 5.3 Machine Exception PC (MEPC)

CSR Address: 0x341

Reset Value: 0x0000\_0000

31

MEPC

When an exception is encountered, the current program counter is saved in MEPC, and the core jumps to the exception address. When an mret instruction is executed, the value from MEPC replaces the current program counter.





### 5.4 Machine Cause (MCAUSE)

CSR Address: 0x342

Reset Value: 0x0000\_0000

31														4	1 0
Interrupt															Exception Code

Detailed:

Bit #	R/W	Description
31	R	Interrupt: This bit is set when the exception was triggered by an interrupt.
4:0	R	Exception Code

Table4: MCAUSE

#### 5.5 MHARTID

CSR Address: 0xF14

Reset Value: Defined

31											10		5	4 3	0
												Cluster ID			Core ID

Detailed:

Bit #	R/W	Description
10:5	R	Cluster ID: ID of the cluster
3:0	R	Core ID: ID of the core within the cluster

Table 5: MHARTID





### 6 Performance Counters

Performance Counters in ZERO-RISCY are placed inside the Control and Status Registers and can be accessed with csrr and csrw instructions. See Table 9.1 for the address map of the performance counter registers

#### 6.1 Performance Counter Mode Register (PCMR)

CSR Address: 0x7A1

Reset Value: 0x0000\_0003

31															1	0
															Saturation	Global Enable

Detailed:

Bit #	R/W	Description
1	R/W	Global Enable: Activate/deactivate all performance counters. If this bit is 0, all performance counters are disabled. After reset, this bit is set.
0	R/W	<b>Saturation:</b> If this bit is set, saturating arithmetic is used in the performance counter counters. After reset, this bit is set.

Table 6: PCMR

#### 6.2 Performance Counter Event Register (PCER)

CSR Address: 0x7A0

Reset Value: 0x0000\_0000

31							16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
							TCDM_CONT	ST_EXT_CYC	LD_EXT_CYC	ST_EXT	LD_EXT	DELAY_SLOT	BRANCH	JUMP	ST	LD	WBRANCH_CYC	WBRANCH	IMISS			INSTR	CYCLES

Detailed:

Bit #	R/W	Description
16	R/W	TCDM_CONT
15	R/W	ST_EXT_CYC
14	R/W	LD_EXT_CYC



Bit #	R/W	Description
13	R/W	ST_EXT
12	R/W	LD_EXT
11	R/W	DELAY_SLOT
10	R/W	BRANCH
9	R/W	JUMP
8	R/W	ST
7	R/W	LD
6	R/W	WBRANCH_CYC
5	R/W	WBRANCH
4	R/W	IMISS
3	R/W	RESERVED
2	R/W	RESERVED
1	R/W	INSTR
0	R/W	CYCLES

#### Table 7: PCER

Each bit in the PCER register controls one performance counter. If the bit is 1, the counter is enabled and starts counting events. If it is 0, the counter is disabled and its value won't change.

In the ASIC there is only one counter register, thus all counter events are masked by PCER and ORed together, i.e. if one of the enabled event happens, the counter will be increased. If multiple non-masked events happen at the same time, the counter will only be increased by one.

In order to be able to count separate events on the ASIC, the program can be executed in a loop with different events configured.

In the FPGA or RTL simulation version, each event has its own counter and can be accessed separately.

#### 6.3 Performance Counter Counter Register (PCCR0-31)

CSR Address: 0x780 - 0x79F

Reset Value: 0x0000\_0000

31

Unsigned Integer Counter Value

Table 4: PCCR0-31

PCCR registers support both saturating and wrap-around arithmetic. This is controlled by the saturation bit in PCMR.



0



Register	Name	Description
PCCR0	CYCLES	Counts the number of cycles the core was active (not sleeping)
PCCR1	INSTR	Counts the number of instructions executed
PCCR2	-	Reserved
PCCR3	-	Reserved
PCCR4	IMISS	Cycles waiting for instruction fetches, i.e. number of instructions wasted due to non-ideal caching
PCCR5	LD	Number of data memory loads executed. Misaligned accesses are counted twice
PCCR6	ST	Number of data memory stores executed. Misaligned accesses are counted twice
PCCR7	JUMP	Number of unconditional jumps (j, jal, jr, jalr)
PCCR8	BRANCH	Number of branches.
		Counts taken and not taken branches
PCCR9	BTAKEN	Number of taken branches.
PCCR10	RVC	Number of compressed instructions executed
PCCR11	LD_EXT	Number of memory loads to EXT executed. Misaligned accesses are counted twice. Every non-TCDM access is considered external (PULP only)
PCCR12	ST_EXT	Number of memory stores to EXT executed. Misaligned accesses are counted twice. Every non-TCDM access is considered external (PULP only)
PCCR13	LD_EXT_CYC	Cycles used for memory loads to EXT. Every non-TCDM access is considered external (PULP only)
PCCR14	ST_EXT_CYC	Cycles used for memory stores to EXT. Every non-TCDM access is considered external (PULP only)
PCCR15	TCDM_CONT	Cycles wasted due to TCDM/log-interconnect contention (PULP only)
PCCR31	ALL	Special Register, a write to this register will set all counters to the supplied value

Table 8: PCCR Definitions

In the FPGA, RTL simulation and Virtual-Platform there are individual counters for each event type, i.e. PCCR0-30 each represent a separate register. To save area in the ASIC, there is only one counter and one counter register. Accessing PCCR0-30 will access the same counter register in the ASIC. Reading/writing from/to PCCR31 in the ASIC will access the same register as PCCR0-30.

Figure 6 shows how events are first masked with the PCER register and then ORed together to increase the one performance counter PCCR.





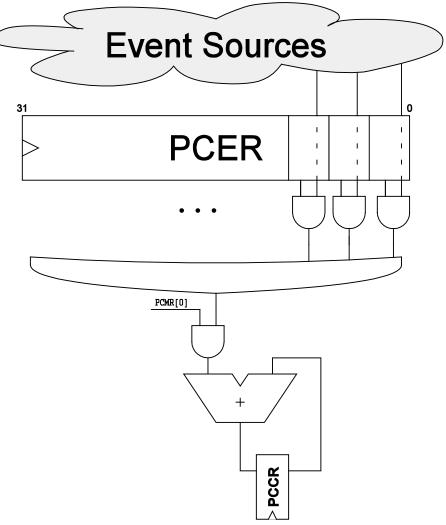


Figure 5: Events and PCCR, PCMR and PCER on the ASIC.





### 7 Exceptions and Interrupts

ZERO-RISCY supports interrupts, exceptions on illegal instructions.

Address	Description
0x00-0x7C	Interrupts 0 – 31
0x80	Reset
0x84	Illegal Instruction
0x88	ECALL Instruction Executed

 Table 5: Interrupt/Exception Offset Vector Table

The base address of the interrupt vector table is given by the boot address. The most significant 3 bytes of the boot address given to the core are used for the first instruction fetch of the core and as the basis of the interrupt vector table. The core starts fetching at the address made by concatenating the most significant 3 bytes of the boot address and the reset value (0x80) as the least significant byte. The boot address can be changed after the first instruction was fetched to change the interrupt vector table address. It is assumed that the boot address is supplied via a register to avoid long paths to the instruction fetch unit.

#### 7.1 Interrupts

Interrupts can only be enabled/disabled on a global basis and not individually. It is assumed that there is an event/interrupt controller outside of the core that performs masking and buffering of the interrupt lines. The global interrupt enable is done via the CSR register MSTATUS.

Multiple interrupts requests are assumed to be handled by event/interrupt controller. When an interrupt is taken, the core gives an acknowledge signal to the event/interrupt controller as well as the interrupt id taken.

### 7.2 Exceptions

The illegal instruction exception and ecall instruction exceptions cannot be disabled and are always active.

### 7.3 Handling

ZERO-RISCY does support nested interrupt/exception handling. Exceptions inside interrupt/exception handlers cause another exception, thus exceptions during the critical part of your exception

handlers, i.e. before having saved the MEPC and MESTATUS registers, will cause those register to be overwritten. Interrupts during interrupt/exception handlers are disabled by default, but can be explicitly enabled if desired. Upon executing an mret instruction, the core jumps to the program counter saved in the CSR register MEPC and restores the MPIE value of the register MSTATUS to IE. When entering an interrupt/exception handler, the core sets MEPC to the current program counter and saves the current value of MIE in MPIE of the MSTATUS register.



#### Debug Unit 8

#### 8.1 Address Map

Address	Name	Description
0x0000-0x007F	Debug Registers	Always accessible, even when the core is running
0x400-0x47F	GPR (x0-x31)	General Purpose Registers Only accessible if the core is halted
0x500-0x5FF	FPR (f0-f31)	Reserved. Not used in the ZERO-RISCY core. First LSP from 0x500-0x57F, then MSP from 0x580- 0x5FF
0x2000-0x20FF	Debug Registers	Only accessible if the core is halted
0x4000-0x7FFF	CSR	Control and Status Registers Only accessible if the core is halted

Table 9: Debug Unit Address Map

Addresses are intended for a bus system with 32-bit wide words. FPR get more address space than GPR because they can be 64-bit wide even in a 32-bit system. Addresses have to be aligned to word-boundaries.

#### **Debug Registers** 8.2

Address	Name	Description
0x00	DBG_CTRL	Debug Control
0x04	DBG_HIT	Debug Hit
0x08	DBG_IE	Debug Interrupt Enable
0x0C	DBG_CAUSE	Debug Cause (Why we entered debug state)
0x40	DBG_BPCTRL0	HW BP0 Control
0x44	DBG_BPDATA0	HW BP0 Data
0x48	DBG_BPCTRL1	HW BP1 Control
0x4C	DBG_BPDATA1	HW BP1 Data
0x50	DBG_BPCTRL2	HW BP2 Control
0x54	DBG_BPDATA2	HW BP2 Data
0x58	DBG_BPCTRL3	HW BP3 Control
0x5C	DBG_BPDATA3	HW BP3 Data
0x60	DBG_BPCTRL4	HW BP4 Control





Address	Name	Description
0x64	DBG_BPDATA4	HW BP4 Data
0x68	DBG_BPCTRL5	HW BP5 Control
0x6C	DBG_BPDATA5	HW BP5 Data
0x70	DBG_BPCTRL6	HW BP6 Control
0x74	DBG_BPDATA6	HW BP6 Data
0x78	DBG_BPCTRL7	HW BP7 Control
0x7C	DBG_BPDATA7	HW BP7 Data
0x2000	DBG_NPC	Next PC
0x2004	DBG_PPC	Previous PC

Table 10: Debug Unit Registers

### 8.2.1 Debug Control (DBG\_CTRL)

Compact:

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
						l	reserve	b							HALT R/W
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
						I	reserve	d							SSTE R/W

Detailed:

Bit #	R/W	Description
16	W1	HALT: When 1 written, core enters debug mode, when 0 written, core exits debug mode. When read, 1 means core is in debug modekkj
0	R/W	SSTE: Single-step enable

Table 11: DBG\_CTRL register

### 8.2.2 Debug Hit (DBG\_HIT)

Compact:

		28	27	26	25	24	23	22	21	20	19	18	17	16
					r	eserved	ł							SLEEP R
15 14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
					r	eserveo	ł							SSTH R/W



#### Detailed:

Bit #	R/W	Description
16	R	SLEEP: Set when the core is in a sleeping state and waits for an event
0	R/W	SSTH: Single-step hit, sticky bit that must be cleared by external debugger

Table 12: DBG\_HIT register

### 8.2.3 Debug Interrupt Enable (DBG\_IE)

Compact:

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
						Т	O BE I	DEFINE	D						
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	reserved			ECAL L	reserved			SAF	SAM	LAF	LAM	BP	ILL	IAF	IAM
				R/W				R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

#### Detailed:

Bit #	R/W	Description
11	R/W	ECALL: Environment call from M-Mode
7	R/W	SAF: Store Access Fault (together with LAF)
6	R/W	SAM: Store Address Misaligned (never traps)
5	R/W	LAF: Load Access Fault (together with SAF)
4	R/W	LAM: Load Address Misaligned (never traps)
3	R/W	BP: EBREAK instruction causes trap
2	R/W	ILL: Illegal Instruction
1	R/W	IAF: Instruction Access Fault (not implemented)
0	R/W	IAM: Instruction Address Misaligned (never traps)
		Table 12: DPC JE register

Table 13: DBG\_IE register

When '1' exceptions cause traps, otherwise normal exceptions.



### 8.2.4 Debug Cause (DBG\_CAUSE)

Compact:

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
IRQ							r	oconio	4						
R							I	eserve	J						
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
													CAUSE		
					reserved	1									

#### Detailed:

Bit #	R/W	Description
31	R	IRQ: Interrupt caused us to enter debug mode
4:0	R	CAUSE: Exception/interrupt number

Table 14: DBG\_CAUSE register

### 8.2.5 Debug Hardware Breakpoint x Control (DBG\_BPCTRLx)

Compact:

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
							rese	rved							
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
							00000000	4							IMPL
						I	reserved	J							R0

Detailed:

Bit #	R/W	Description
0	R	IMPL: ZERO-RISCY does not implement hardware breakpoints. Always read as 0.
		Table 15: DPC PDCTPL v register

Table 15: DBG\_BPCTRLx register





### 8.2.6 Debug Next Program Counter (DBG\_NPC)

Compact:

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
							NPC[	31:16]							
							R/	W							
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
							NPC	[15:0]							
							R/	W							

#### Detailed:

Bit #	R/W	Description
31:0	R/W	NPC: Next PC to be executed

Table 16: DBG\_NPC register

When written core jumps to PC.

### 8.2.7 Debug Previous Program Counter (DBG\_PPC)

Compact:

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
							PPC[3	31:16]							
							F	2							
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
							PPC[	[15:0]							
							F	2							

Detailed:

Bit #	R/W	Description
31:0	W	PPC: Previous PC, already executed
		Table 17: DBG_PPC register

Values of PPC and NPC when entering debug mode:

Reason	PPC	NPC	Cause	GDB Sigval
ebreak	ebreak instruction	next instruction	BP	TRAP
ecall	ecall instruction	IVT entry	ECALL	TRAP
illegal instruction	illegal instruction	IVT entry	ILL	ILL
invalid mem access	load/store instruction	IVT entry	LAF/SAF	SEGV
interrupt	last instruction	IVT entry	?	INT



Reason	PPC	NPC	Cause	GDB Sigval
halt	last instruction	next instruction	?	TRAP
single-step	last instruction	next instruction	?	TRAP

 Table 18: NPC/PPC when entering Debug Mode

#### 8.3 Control and Status Registers

Address	Name	Description
0x4000	CSR 0 = 0x000	CSR
0x7FFC	CSR 4095 = 0xFFF	CSR

Table 19: Debug CSR Mapping

Can only be accessed when core is in debug mode.

#### 8.4 Interface

Signal	Direction	Description
debug_req_i	input	Request
debug_gnt_o	output	Grant
debug_rvalid_o	output	Read data valid
debug_addr_i[14:0]	input	Address for write/read
debug_we_i	input	Write Enable
debug_wdata_i[31:0]	input	Write data
debug_rdata_o[31:0]	output	Read data
debug_halted_o	output	Is high when core is in debug mode
debug_halt_i	input	Set high when core should enter debug mode
debug_resume_i	input	Set high when core should exit debug mode

Table 20: Debug Interface

debug\_halted\_o, debug\_halt\_i and debug\_resume\_i are intended for cross-triggering between multiple cores. They are not required for single-core debug, thus debug\_halt\_i and debug-resume\_i can be tied to 0.

debug\_halt\_i and debug\_resume\_i should be high for only one single cycle to avoid deadlock issues.